



ARVY | Robot Vision

<i>CONTENT</i>	OPERATOR-TRAINING	MAINTAINER-TRAINING
THEORETICAL PART		
INTRODUCTION TO IMAGE PROCESSING		X
MEASURING PRINCIPLE Q-GAGE AND TIB / MEASURING PROCEDURE / SENSORS	X	X
USER INTERFACE ARVY	X	X
CREATING AND TEACHING PRODUCTS FOR PATH AND TOOL		X
SETTING UP THE SYSTEM, CONTROL CABINET / HARDWARE	X	X
DATA SAVING		X
FAULT DIAGNOSIS LOG FILES		X
ERROR DIAGNOSIS / INTERPRETATION OF ERROR IMAGES	X	X
OPTIMISING AND PARAMETERISING PRODUCTS		X
CALIBRATING THE SYSTEM / ZERO MEASUREMENT		X
SETTING LIMIT VALUES AND OFFSETS		X
SENSOR EXCHANGE		X
PRACTICAL PART		
GENERAL SOFTWARE OPERATION	X	X
INTERFACES AND COMMUNICATION	X	X
ADDING AND CALIBRATING SENSORS.		X
SETTING UP AND PARAMETERISING THE PRODUCTS		X
ZERO MEASUREMENT		X
DISPLAY LIMIT VALUES AND OFFSETS		X
SHOW THE MEASURING POINTS ON THE REAL OBJECT		X
CARRYING OUT DATA BACKUP		X
CHECKING THE CALIBRATION		X
ERROR HANDLING / LOG FILES		

Bestellnummer	Beschreibung	
COS.AR.01	Operator Training	One-day course, max. 5 participants
COS.AR.02	Maintainer Training	Two-day course, max. 5 participants